

ICSR 2013 Workshop: Taking Care of Each Other: Synchronisation and Reciprocity for Social Companion Robots	
When: Sunday, October 27,2013 Where: TBD	Begin - End
Introduction to the general topic of the workshop and the participants	09:00-09:30
<ul style="list-style-type: none"> • Do we need grounding for intuitive HRI? Astrid Weiss • Synchrony and reciprocity for social companion robots: benefits and challenges Tamara Lorenz 	
Position statements and discussion towards common grounding	09:30-11:00
<ul style="list-style-type: none"> • Do We Need Compassion in Robots? Frank Broz and Hagen Lehmann • Dominance, Compassion, and Evolved Social: Behaviour: Advisable Roles and Limits for Companion Robots Joanna J. Bryson • A Joint Action Approach to Use of Synchrony and Imitation in Robot Interactions Tehran J. Davis, Kerry L. Marsh, Timothy D. Gifford, Anjana N. Bhat • Using a gaze-cueing paradigm to examine human readiness to engage in interactions with robots Agnieszka Wykowska, Eva Wiese, Hermann J. Müller • Robots as companions and therapists in elderly care Jorge Gallego-Perez, Manja Lohse, and Vanessa Evers • Social companion robots in eldercare – who gains and who loses? Susanne Frennert 	
Coffee Break and Posters	11:00-11:30
<ul style="list-style-type: none"> • Attitudes of Children Towards Dancing Robot: Nao: A Kindergarden Observation Arzu Güneysu, Iclal Karatas, Okan Asik and Bipin Indurkhya • “How to train your robot” – Developing a strategy for enhancing the quality of social interaction with a companion robot through user feedback Praminda Caleb-Solly • Accurate robotic replication of human head gestures Nigel Crook, Steve Barker, Alison Honour, Michael Pilling, Khaled Hayatleh, and Neil Fellows • Social Shaping of Interactions between Older Adults and the Seal-Like Robot PARO Wan-Ling Chang, SelmaSabanovic, and Lesa Huber • Improving the Development of Companion Robots for Elderly Care by Integrating Meaningful Cognitive Functions Torsten Metzler, Udo Lindemann • Modeling Robots with Anticipations Generated by Analogy-Making Georgi Petkov and Luiza Shahbazyan 	

Break-Out Groups I: What are the building blocks for social interaction with companion robots? Discussion on the characterization of “social interaction” and influencing factors	11:30-12:30
Lunch	12:30-13:30
Bringing the discussions together (all participants)	13:30-14:30
Break-Out Groups II: From influencing factors to success measures (break out groups)	14:30-15:30
Coffee Break	15:30-16:00
Bringing the discussions together and reflect on Potential future interaction use cases for compassionate companion robots (all participants)	16:00 – 16:30
Wrap-up, summary of the topics and definition of follow-up	16:30-17:00